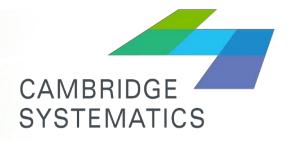
TransModeler Training 5- Simulation Types

presented to

Caltrans, District 1-Eureka

presented by

Shaghayegh (Rira) Shabanian, CS



Think *Forward*

July & August 2018

Model Review

- Result of ODME for AM is coded to run DTA and simulation in AM
- Still need to review the results of ODME: why at some locations output volume is significantly different from the observed volume
- Check un-signalized intersection for proper control policy (yield/stop sign)

Review signal timing. Still see some problems**

 are ring/barriers correct? Are concurrent movements going together?
 Are permitted/protected green used correctly?
 Is each phase associated with the right detector? Are detector
 locations/size/mode correct?
 Are right turns coded correctly? (default is RTOR)
 Are signal timing (cycle length/offset/lost time/recall mode) coded correctly?

Use weighted average to define vehicle fleet for AM and PM***



Simulation Types

DTA

- » Route Choice When more than one route is available
- » Outputs segment and turning travel time

One-shot Simulation

- » Network Loading When only one route is available or historical travel time is available
- » Outputs segment volume and congested time
- Batch
 - » Multiple one-shot simulation to achieve higher level of confidence
 - » # of runs are associated with the desired confidence level
- PlayBack
 - » When simulation is recorded or trajectory file is saved in output.



DTA vs. STA

- Both implement user equilibrium to assign vehicles to available routes.
- In DTA, Network and demand can change over time during the simulation (temporary lane blockage, demand fluctuations)
- In DTA, shortest path can change in each interval.
- In DTA, capacity and storage limit the entering vehicles, queue forms
- In DTA, congestion in one interval affects the next interval route choice.



Notes on DTA

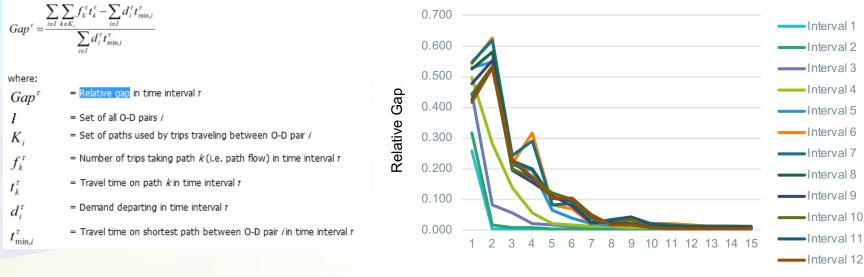
- DTA in congested networks can hard to converge. However, it may still provide more realistic results compared to static assignment, *but further details are needed*.
- It is reasonable to adjust the link and turning movement travel time from a DTA model, if it is against observed data.
- Specially, observed data can be used to set a limit on maximum delay or minimum speed on links or at intersections.
- This helps to get a more realistic simulation results out of a not-completely converged DTA.
- However, difficulty exists in moving this into future scenario evaluations



DTA Convergence

Relative GAP, (similar to the STA definition)

» No mathematical guarantee of convergence for stochastic simulation based model



Iteration

- Still, might be better than STA to replicate real-world congestion
- If not completely converged, travel time table should be validated/modified before being used in one-shot assignment.

DTA - Settings

Simulatio	on Options		? ×
Mode	Tools Macros		
Run			
⊖ s	mulation	○ Playback	
⊚ D	ynamic Traffic Assignment	O Signal Emulation	
OB	atch Simulation		
Dyna	mic Traffic Assignment Settin	gs	
	Target Gap 0.5%	Start Iteration	1
	Interval (min.) 15 🛛 🗸	Maximum Iterations	10
C	emand Factor 100.0%	Path Update Threshold	5.0%
	Start from Free Flow	Choose Output File	·s
	Suspend Output During A	ssignment	
	Standard Deviation of Trip	Travel Time Start at	10
Optio	ins		
Th	reading Model Default	✓ Routing Threads M	ax 🗸
	uppress Startup Warnings	Simulation Threads M	ax ~
		ОК	Cancel

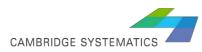


7

DTA - Result

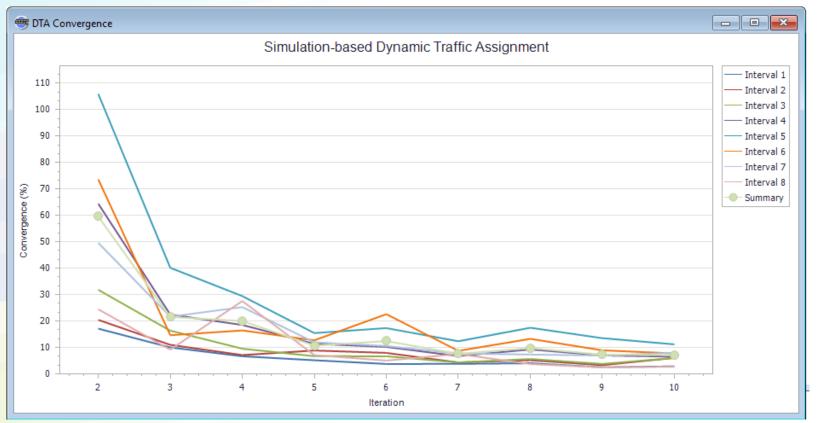
Relative Gap

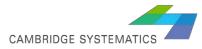
hunning Traffi	c Assignment	4	12.4	11.2	11.8	12.1	11.5	10.0	10.2	11.4	
ynamic fram	c Assignment	×									
teration	Convergence	9	13.5	12.9	15.1	13.7	14.0	12.8	14.3	13.9	
		_ 5	4.9	5.3	4.2	4.1	6.0	4.8	5.3	4.9	
	59.57%						10.4			10.4	
	21.55%	5	2.5	2.4	2.4	2.5	2.7	2.3	2.5	2.5	
	20.02%	6									
	10.72%	6									
	12.44%	4	21.6	19.0	27.4	20.6	20.0	16.4	16.0	19.3	
	7.64%										
		2	3.3	2.3	1.8	2.5	Results Su	25		25	
	9.75%	6 0	2.7	0.4	2.3	2.4	Results St	immary			
	7.32%	6 8	0.3	3.6	1.7	1.3		D	ynamic Traff	ic Assiann	hent
0	7.07%	0	2.0	3.6	4.3	3.4			jiiaiiie iiaii	ie i i song i i i	
°		0	0.0	0.0							
		1	5.4	4.2		5.4	Assignment did not converge in 10 iterations Final Gap = 7.072781%. Errors and Report Lines Logged				s
		4	1.4	3.8	3.3	2.1					
		9	40.4	40.7	43.6	47.8					
		6	2.4	2.5	2.6	2.7	War	Warnings: n/a Report Lines: 9			
		3	0.3	0.3	0.3	0.3					
							Show <u>V</u>	<u>V</u> arnings	Show <u>R</u> ep	ort	<u>C</u> lose
		0		5.1	0.0	2.7	0.0	8.6	4.4	3.3	
		4	17.2	5.7	28.9	18.9	21.4	9.4	16.7	16.5	
	L sizz	, 1	9.7	8.3	9.7	20.7	15.8	21.8	20.1	15.4	
		5			0.0	0.0			0.0	0.0	
Current Ite	eration 10					ľ					1
	eshold 0.5%	-				I.					



DTA - Result

Relative Gap





DTA – Historical Travel Time Tables

Most important outputs of DTA are:

Historical Travel Times.bin Turning Delays.bin

Other files include: X* DTA Convergence.bin X trips missed turns.bin X trips no path.bin X trips.bin X trips.pth Path.pth Segment Time Variability

All of these files can be very helpful to evaluate the route choice that DTA creates, and also to spot issues/ problems. Please read and explore these files. (.bin files can be open separately, *.pth files can be accessed through interface toolbars such as critical path, etc)



DTA – Evaluation

Sort from highest delay in each 15 minute and start from top locations not only the magnitude of delay, but its fluctuation over time is important and shows DTA was not appropriately converged.

taview1 - Tu												
FromLink	Node	ToLink Dir Type	Facility De	lay_0700 D e	elay_0715 De	lay_0730 D	elay_0745 De	lay_0800 D <i>e</i>	lay_0815 Do	elay_0830 Del	av 0845	Delay
4598	842641	4452 NW L		133.9	176.6	177.7	176.5	111.9	175.7	175.0	53.8	147.6
8012	842043	5107 SE T		75.8	69.1	57.7	37.6	65 7	73.9	68.4	67.3	64.4
8023	53	4841 S T		68.1	102.1	117.5	344.7	630.2	290.2	238.0	11.6	225.3
6791	842755	8014 E T		66.9	71.7	76.5	64.8	62.8	03.6	50.1	56.9	63.7
6791	842755	6789 E L		63.9	70.7	72.5	41.9	69.5	66.5	58.0	67.7	63.8
6789	842755	8014 SW L		58.7	64.1	63.1	95.3	59.2	70.4	63.5	68.9	67.9
5253	842043	5107 SW L		45.9	40.4	40.7	43.6	47.8	46.7	48.9	66.6	47.6
5068	842755	6791 N L		45.3	44.1	67.5	63.8	60.0	53.1	64.1	50.9	56.1
4086	842370	4641 E L		41.3	1.5	15.1	0.3	13.9	26.8	14.9	15.7	16.2
5079	842709	4614 NE L		39.7	49.8	53.5	52.8	51.9	54.1	54.9	54.3	51.4
4783	842757	4796 N L		39.1	37.5	38.9	40.2	16.0	27.0	28.6	46.8	34.3
7642	842709	4331 S₩ T		29.4	51.4	70.8	53.9	50.8	57.7	51.7	53.7	52.4
7642	842709	4613 SW L		28.7	50.3	58.7	61.0	59.6	67.4	84.8	58.6	58.6
8030	842447	4951 S L		27.5	22.8	20.5	52.1	74.0	36.6	9.2	13.2	32.0
4331	842709	4614 N L		27.3	32.2	6.5	71.1	37.8	21.9	50.6	73.4	40.1
3765	842150	4822 E L		26.9	24.6	22.6	20.1	20.7	22.3	21.3	25.0	22.9
4614	842709	4613 E T		26.2	33.6	41.4	39.8	41.4	47.2	42.1	41.5	39.2
7964	842449	4597 W T		25.5	19.7	23.0	20.4	22.6	20.7	19.8	22.8	21.8
4614	842709	7642 E L		25.1	30.2	38.3	53.5	50.8	45.5	52.7	48.5	43.1
8021	842427	4101 E T		23.8	21.3	19.2	16.7	19.1	14.5	17.2	18.3	18.8
5253	842708	4612 NE R		22.1	0.3	23.1	5.3	5.2	0.3	0.8	0.4	7.2
7964	842449	8030 ₩ L		22.0	19.1	22.2	27.7	19.4	15.5	16.8	22.8	20.7
4796	842757	7616 E L		20.0	19.9	23.8	28.6	37.0	22.8	20.9	26.2	24.9
5253	842708	7990 NE L		20.0	21.7	23.2	21.5	21.5	23.2	24.5	23.3	22.4
4331	842709	4613 N R		19.8	19.0	29.8	29.7	42.1	38.3	41.3	46.7	33.3
7633	65	8024 N T		19.4	16.8	14.9	15.5	12.0	15.5	13.0	14.6	15.2
3891	842264	5045 E L		19.4	76.1	5.8	65.0	49.2	5.4	48.3	32.5	37.7

Running One-shot simulation

- DTA outputs paths and segment travel time/turning movement delays, but does not provides link volumes
- To obtain link volumes, a one-shot simulation is run WITH THE RESULTS OF DTA AS INPUT
- This run will duplicate the last iteration in DTA, and will output segment and turning movement volume
- Now we can compare the turning movement volumes with original observed intersection counts!
- Please note that there will be a discrepancy between model volume after ODME, and model volume after simulation. Remember that ODME was static process that would ignore signal timing, capacity limitation, etc. the more congested a network is, the higher will be this discrepancy.



Running One-shot simulation

cenari										
Curre	ent AM				~	+ ×	T			
etup	Network	Input Outp	out Routing	Ор	tions					
Route	Choice									
	Metho	d Stochastic	Shortest Path				\sim			
	Minimiz	e Travel Tim	e							
			-							
L	ink Exclusior	None					\sim			
Travel	Time and Tu	uming Delay								
Info		Filename					_			
	orical	Output\AM\Historical Travel Times.bin								
		Output\AIVI\	Historical Ira	/er Ti	mes.bin		_			
	lated									
Tur	ning Delay	Output\AM\	Turning Delay	/s.bir	1		•			
First	t Time Field(s) Delay_0700)	\sim	Num. Intervals	8	* *			
	Start Time	07:00:00	Ŀ	+	Interval (min)	15				
Global	l Turning Del	ays								
Mo	vement				D	elay (sec)			
Rigi	ht Turn			10.0						
Thr	ough			0.0						
Left Turn			30.0							
U-Turn						60.	0			
<mark>∠ E</mark> r	nforce global	turning delay	/s as minimur	n						

OK



Simulation Result

- ➤ Compare segment volume vs coded segment count identify locations with high discrepancy which of these locations were better replicated during ODME? Pay attention to locations where model volume is zero so far I observed model outputs are systematically lower than counts run one time with 15% blanket increase in demand (Demand→ OD Matrices→ Trip Matrix Settings→ Unit scaling factor)
- Compare turning movement volume vs coded intersection counts
- Compare model route travel time vs floating car runs make a selection set of nodes that define routes start/end, use shortest path skim in the output feature.





 Explore ODME for AM Count at 4&H, More volume on H SB than on 4 WB!
 5&H * Count at 5&E make sure TurningCount.bin is correct if you change anything in TurningCount.bin, you need to update segment synthetic count around modified intersections. ODME should be re-run

- Run DTA for AM (with 50 iterations), evaluate the outputs watch the simulation during the run
- Run one-shot simulation for AM, compare modeled and observed volume and travel time repeat it with 15% increased in demand

